# Runsen Xu

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# **m** EDUCATION

#### The Chinese University of Hong Kong (CUHK)

Hong Kong, China

Ph.D. Student at MMLab, Information Engineering

Aug. 2022 – June 2026 (Expected)

• Advisor: Prof. Dahua Lin

#### **Zhejiang University (ZJU)**

Hangzhou, China

B.Eng. in Computer Science and Technology

Sep. 2018 – June 2022

• Pursuit Science Class (Qiushi Honor's Program, 20 students only), Chu Kochen Honors College

#### Publications

(Some papers are under review. \* equal contribution, # project lead, ⊠ corresponding author)

- [1] Changing Grounding: 3D Visual Grounding in Changing Scenes
  Miao Hu, Zhiwei Huang, Tai Wang, Jiangmiao Pang, Dahua Lin, Nanning Zheng, Runsen Xu
  In submission, 2025. [Paper]
- [2] MMSI-Bench: A Benchmark for Multi-Image Spatial Intelligence Sihan Yang\*, Runsen Xu\*#, Yiman Xie, ..., Dahua Lin, Tai Wang™, Jiangmiao Pang™ arXiv Preprint, 2025. [Paper]
- [3] Multi-SpatialMLLM: Multi-Frame Spatial Understanding with Multi-Modal Large Language Models Runsen Xu, Weiyao Wang, Hao Tang, ..., Fu-Jen Chu, Dahua Lin, Matt Feiszli, Kevin J. Liang arXiv Preprint, 2025. [Paper]
- [4] PointLLM-V2: Empowering Large Language Models to Better Understand Point Clouds Runsen Xu\*, Shuai Yang\*, Xiaolong Wang, Tai Wang⊠, Yilun Chen, Jiangmiao Pang⊠, Dahua Lin Transactions on Pattern Analysis and Machine Intelligence (TPAMI), 2025. [Paper]
- [5] VLM-Grounder: A VLM Agent for Zero-Shot 3D Visual Grounding Runsen Xu, Zhiwei Huang, Tai Wang, Yilun Chen, Jiangmiao Pang<sup>™</sup>, Dahua Lin Conference on Robot Learning (CoRL), 2024. [Paper]
- [6] PointLLM: Empowering Large Language Models to Understand Point Clouds Runsen Xu, Xiaolong Wang, Tai Wang<sup>™</sup>, Yilun Chen, Jiangmiao Pang<sup>™</sup>, Dahua Lin European Conference on Computer Vision (ECCV), 2024, Best Paper Candidate. [Paper]
- [7] MV-JAR: Masked Voxel Jigsaw and Reconstruction for LiDAR-Based Self-Supervised Pre-Training Runsen Xu, Tai Wang, Wenwei Zhang, Runjian Chen, Jinkun Cao, Jiangmiao Pang<sup>™</sup>, Dahua Lin Computer Vision and Pattern Recognition (CVPR), 2023. [Paper]
- [8] VFlowOpt: A Token Pruning Framework for LMMs with Visual Information Flow-Guided Optimization Sihan Yang, Runsen Xu, Chenhang Cui, Dahua Lin, Tai Wang, Jiangmiao Pang International Conference on Computer Vision (ICCV), 2025. [Paper]
- [9] **OST-Bench: Evaluating the Capabilities of MLLMs in Online Spatio-temporal Scene Understanding** Jingli Lin\*, Chenming Zhu\*, **Runsen Xu**, Xiaohan Mao, Xihui Liu, Tai Wang, Jiangmiao Pang arXiv Preprint, 2025. [Paper]
- [10] Learning Video Generation for Robotic Manipulation with Collaborative Trajectory Control Xiao Fu, Xintao Wang, Xian Liu, Jianhong Bai, Runsen Xu, Pengfei Wan, Di Zhang, Dahua Lin arXiv Preprint, 2025. [Paper]
- [11] **Grounded 3D-LLM with Referent Tokens**Yilun Chen\*, Shuai Yang\*, Haifeng Huang\*, Tai Wang, **Runsen Xu**, Ruiyuan Lyu, et al. arXiv Preprint, 2024. [Paper]
- [12] MMScan: A Multi-Modal 3D Scene Dataset with Hierarchical Grounded Language Annotations Ruiyuan Lyu\*, Tai Wang\*, Jingli Lin\*, Shuai Yang\*, Xiaohan Mao, Yilun Chen, Runsen Xu, et al.

Neural Information Processing Systems, Datasets and Benchmarks Track (NeurIPS), 2024. [Paper]

- [13] Chat-Scene: Bridging 3D Scene and Large Language Models with Object Identifiers Haifeng Huang, Yilun Chen, Zehan Wang, Rongjie Huang, Runsen Xu, et al. Neural Information Processing Systems (NeurIPS), 2024. [Paper]
- [14] EmbodiedScan: A Holistic Multi-Modal 3D Perception Suite Towards Embodied AI Tai Wang\*, Xiaohan Mao\*, Chenming Zhu\*, Runsen Xu, et al. Computer Vision and Pattern Recognition (CVPR), 2024. [Paper]
- [15] Fine-Grained Cross-View Geo-Localization Using a Correlation-Aware Homography Estimator Xiaolong Wang, Runsen Xu, Zuofan Cui, Zeyu Wan, Yu Zhang Neural Information Processing Systems (NeurIPS), 2023. [Paper]
- [16] CO<sup>3</sup>: Cooperative Unsupervised 3D Representation Learning for Autonomous Driving Runjian Chen, Yao Mu, Runsen Xu, Wenqi Shao, Chenhan Jiang, Hang Xu, Zhenguo Li, Ping Luo International Conference on Learning Representations (ICLR), 2023. [Paper]
- [17] RNIN-VIO: Robust Neural Inertial Navigation Aided Visual-Inertial Odometry in Challenging Scenes Danpeng Chen, Nan Wang, Runsen Xu, Weijian Xie, Hujun Bao, Guofeng Zhang International Symposium on Mixed and Augmented Reality (ISMAR), 2021. [Paper]
- [18] **LIFE: Lighting Invariant Flow Estimation**Zhaoyang Huang\*, Xiaokun Pan\*, **Runsen Xu**, Yan Xu, Kachun Cheung, Guofeng Zhang, Hongsheng Li arXiv Preprint, 2021. [Paper]

#### **Q** RESEARCH EXPERIENCES

#### OpenRobotLab, Shanghai AI Laboratory

Jan. 2025 - June 2025

Research intern Shanghai, China

• Worked on multi-modal large language models (MLLMs) for spatial understanding.

#### Perception Pillar, FAIR, Meta

June 2024 - Dec. 2024

Research scientist intern

Menlo Park, CA, USA

• Worked on multi-modal large language models (MLLMs) for spatial understanding.

#### OpenRobotLab, Shanghai AI Laboratory

Mar. 2023 - June 2024

Research intern Shanghai, China

• Worked on 3D vision and language, multi-modal large language models (MLLMs).

# Shanghai AI Laboratory

Nov. 2021 - July 2022

Research intern Shanghai, China

• Worked on self-supervised 3D representation learning.

## 3D Vision Group, CAD&CG State Key Lab, Zhejiang University

Mar. 2020 - Oct. 2021

Research assistant

Hangzhou, Zhejiang, China

• Worked on indoor AR navigation, indoor navigation solutions for individuals with visual impairments, and optical flow estimation.

#### Mobile SLAM, SenseTime Group Ltd.

Mar. 2021 - June 2021

Research intern Hangzhou, Zhejiang, China

• Worked on neural inertial navigation with IMU data.

### **₹** Selected Awards

ECCV Best Paper Candidate	2024
• Hong Kong PhD Fellowship (most prestigious scholarship for Ph.D. studies in Hong Kong)	
CUHK Vice-Chancellor's PhD Scholarship	
Outstanding Graduates of Zhejiang University	2022

•	Outstanding	Undergraduate Thesis	
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• National Scholarship (highest honor nationwide for Chinese undergraduates)

20222019

# *★* TEACHING

• Teaching Assistant: IERG4998 - Final Year Project

Spring 2023

• Teaching Assistant: IERG4998 - Final Year Project

Fall 2022

# **COMPUTER AND LANGUAGE SKILLS**

• Programming Proficiency: Python, C/C++, PyTorch, Shell Script, Java, MATLAB, JavaScript/HTML/CSS

• Language Proficiency: Mandarin (native speaker), English (proficient)